

This walkthrough assumes that you know how to Create a new project including selecting a parameter file.

This walkthrough requires a file which you can download from the website. This file is called LidarExample.zip and must be unzipped before you start.

- 1. Create a new file called LidarExample.
- 2. Select the options shown below.



3. In the dialog box that appears, select the previously downloaded file LidarExample.csv. Your screen should now look similar to this.

LDNet Design CSV/TXT File li	mporter for LIDAR	data : D:\DATA\CO	.DNetProfile\Basic\	LidarExample.COL	DProfile	
	D-1DATALCOL	DNetProfile\EE\Lid				
	D:\DATA\COL		arexample.csv			
Load Import Template						
Jncheck the box above e column if it should not						
be imported:						
elect the type of data in						
			~	~	~ ~	
		740766.12	6303152.73	667.77	2	
hould not be imported. hese would normally be		740766.74	6303152.91	667.77	2	
ows containing header information.		740767.24	6303152.99	667.8	2	
		740767.75	6303152.99	667.8	2	
		740773.5	6303150.73	667.77	2	
		740774.56	6303150.87	667.8	2	
	\checkmark	740774.56	6303150.87	667.8	8	
	\checkmark	740774.92	6303150.94	667.78	8	
		740775.14	6303150.99	667.8	2	
		740775.47	6303150.99	667.8	8	
		740775.75	6303150.99	667.78	2	
		740776.81	6303150.98	667.78	2	
		740776.81	6303150.98	667.78	8	
		740769.3	6303151.97	667.78	2	
		740769.86	6303151.92	667.78	8	
	\checkmark	740770.14	6303151.99	667.78	2	
nts : 59414						



4. Select the Button Load Import Template as shown below.

COLDNet Design CSV/TXT File In	mporter for LIDAR d	ata : D:\DATA\COL	DNetProfile\Basic\	LidarExample.COLD	Profile	_	
	late						
Select File to Import	D:\DATA\COLDN	etProfile\EE\Lidar					
Load Import Template							
Uncheck the box above the column if it should not be imported:					V		
Select the type of data in the column.		×	~	~	~		
Uncheck any rows that		740766.12	6303152.73	667.77	2		^
should not be imported. These would normally be	M	740766.74	6303152.91	667.77	2		
rows containing header		740767.24	6303152.99	667.8	2		
information.		740767.75	6303152.99	667.8	2		
		740773.5	6303150.73	667.77	2		
		740774.56	6303150.87	667.8	2		
		740774.56	6303150.87	667.8	8		
		740774.92	6303150.94	667.78	8		
		740775.14	6303150.99	667.8	2		
		740775.47	6303150.99	667.8	8		
		740775.75	6303150.99	667.78	2		
		740776.81	6303150.98	667.78	2		
		740776.81	6303150.98	667.78	8		
		740769.3	6303151.97	667.78	2		
		740769.86	6303151.92	667.78	8		
		740770.14	6303151.99	667.78	2		
		740770.74	6303151.89	667.76	2		
		740771.57	6303151.73	667.77	2		
		740767 32	6303152 31	667 78	2		×
. of Points : 59414							

5. Select the downloaded file **LidarExample.COLDNeLidarImportTemplate.** The template file stores information of the type of data in each column and the Feature Code file as highlighted below.

COLDNet Design CSV/TXT File	Importer for LIDAR	data : D:\DATA\CO	LDNetProfile\Basic\	LidarExample.COL	DProfile		
	plate						t C
		NetProfile\EE\Lida	Example cov				
Select File to Import							
Load Import Template	D:\DATA\COLD	NetProfile\EE\Lida		larImportTemplat			
Uncheck the box above							
the column if it should not be imported:							
Select the type of data in							
the column.		East 🗸	North ~	Level ~	Feature Code 🗸		
Uncheck any rows that		740766.12	6303152.73	667.77	2		L
should not be imported. These would normally be		740766.74	6303152.91	667.77	2		1
rows containing header information.		740767.24	6303152.99	667.8	2		1
		740767.75	6303152.99	667.8	2		1
		740773.5	6303150.73	667.77	2		1
		740774.56	6303150.87	667.8	2		1
		740774.56	6303150.87	667.8	8		1
		740774.92	6303150.94	667.78	8		1
		740775.14	6303150.99	667.8	2		1
		740775.47	6303150.99	667.8	8		1
		740775.75	6303150.99	667.78	2		1
		740776.81	6303150.98	667.78	2		1
		740776.81	6303150.98	667.78	8		
		740769.3	6303151.97	667.78	2		1
		740769.86	6303151.92	667.78	8		
		740770.14	6303151.99	667.78	2		
		740770.74	6303151.89	667.76	2		1
		740771.57	6303151.73	667.77	2		
		740767 32	6303152 31	667 78	2		L
Load Feature Code File	D:\DATA\COLD	NetProfile\EE\Lida		atureCodeList			
of Points : 59414							

The feature code file stores the point cloud feature code classifications. More information on this is provided later in the walkthrough.

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ł	:Profile\EE\Li					
	tProfile\EE\Li			darImpo	rtTempla	
	2		2		M	M
2	ast	`	North ~	Level		Feature Code
ų	740766.12		6303152.73	667.77	,	2
ū	740766.74		6303152.91	667.77	,	2
ū	740767.24		6303152.99	667.8		2
u	740767.75		6303152.99	667.8		2
ū	740773.5		6303150.73	667.77	,	2
ų	740774.56		6303150.87	667.8		2
ų	740774.56		6303150.87	667.8		8
ų	740774.92		6303150.94	667.78	3	8
ū	740775.14		6303150.99	667.8		2
u	740775.47		6303150.99	667.8		8
ų	740775.75		6303150.99	667.78	3	2
ü	740776.81		6303150.98	667.78	3	2
ų	740776.81		6303150.98	667.78	3	8
ų	740769.3		6303151.97	667.78	3	2
u	740769.86		6303151.92	667.78	3	8
12	740770.14	_	6303151.99	667.78	3	2
	tProfile\EE\Li					

You will be given the opportunity to save the template at the next step in case you have made changes. Select No

Save as Template	×
Do you want to save these settings as a template befo	ore you proceed?
Yes No	Cancel

You will then be returned to the main form as shown below.





7. Select the option on the menu bar Feature Codes.

C COL	DNet Profile Version: 1.0.1 Licenced	to:							
	Design Parameters & Libraries			Tables	Feature Codes Reports			Clear Undo/Redo Lists	Job History Add Offl
Creat	e DTM from Lidar Deviation Poir				Width (m): 10	Feature Cod			

The form shown below will be displayed.

Code	Description	Survey Code	Visible	Colour	Pixel Size	Pen Width	Style		Include in Triangulation	Aerial Points	Point Count
	Point of intersection(PI)				10	5	х	~			3
	Ground				1	1	Pixel	\sim			36336
;	Veg >2m				1	1	Pixel	\sim			7500
	Veg <2m				1	1	Pixel	\sim			5418
,	Building				1	1	Pixel	\sim			1441
;	Model Key Points				1	1	Pixel	\sim			1402
1	Conductor 11kV				1	1	Pixel	\sim			2748
1	Grid Structure Towers				1	1	Pixel	\sim			287
3	Veg offset >0.5<1.5m				1	1	Pixel	\sim			8
4	Veg offset >1.5<2.5m				1	1	Pixel	\sim			33
25	Veg offset >2.5<3.5m				1	1	Pixel	\sim			212
26	Veg offset >3.5<4.5m				1	1	Pixel	\sim			489
27	Veg offset >4.5<5.5m				1	1	Pixel	\sim			503
28	Veg offset >5.5<6.5				1	1	Pixel	\sim			527
9	Veg offset >6.5				1	1	Pixel	\sim			1953

Note that different lidar providers typically use different point cloud classifications or feature codes. In this example Feature Code 1 is the pole locations.

Here you can change the colours of the classifications as well as the pixel and pen size and style of the point.

Note that there is a column with the heading **Include in Triangulation.** Any ground point data must have this ticked to be used when the Digital Terrain Model (DTM) is built. Do not include any points that are not ground points.

8. Close this form.

The processing of Lidar data into a Digital Terrain Model is a very computer intensive task. The software uses a multithreaded solution for this, so all CPU's in your computer are used to create the model. The speed of this process depends on the number of cores and threads available on your computer, speed of memory and speed of disk drives.

9. Select Create DTM from Lidar as highlighted below.

C co	LDNet Profile Version: 1.0.1 Licenced	to:								
File	Design Parameters & Libraries	Terrain Data Profiles		Tables	Tools	Feature Codes	Clone Design		Undo	Clear Undo/Redo Lists
Crea	te DTM from Lidar Deviation Poin	t Deviation at all poles	Clear Point Sele	ection Er	nvelope	Width (m) : 10	Feature Cod	erate Profi	le	



A form will be displayed to show the progress of the creation of the DTM.

	Digital Terrain Model Progress	
		Triangulation Progress
Collect Terrain Points	Thread1	
Setting up Grids - Pass 1	Thread2	
Setting up Grids - Pass 2	Thread3	
	Thread4	
Removing Empty Cells	Thread5	
Start Triangulation	Thread6	
Triangulation Completed. Cleaning up Grids	Thread7	
Removing Duplicates	Thread8	
	Thread9	
Merging Cells	Thread10	
Model Completed	Thread11	
	Thread12	

On the right hand side of this form there is a Progress Bar displayed for each thread.

Once the process is finished, this form will be closed, and you will be returned to the main screen which will look like the image below.





Zooming in will show the triangles that have been created.



10. Turn off the triangles by clicking on the highlighted Show Triangles.

The next step is to create the centreline. You will see points marked with a large red cross as shown below.



11. Select **Deviation Point** as highlighted in the menu on the image above then select the red cross on the left of the screen by moving the mouse ove the point and pressign the left hand mouse button.



The speed and number of points found depends on how far you have zoomed in and the point density. Typically, with Lidar, the program will find a number of points near in the vicinity of where you clicked the muse button. When multiple points are found, you will then need to select the required point from the list displayed to you.

12. Find the Point 18184 as highlighted in the screen below. Note that with this lidar file, the point is marked as a Feature Code Type 1 which is a pole location. The press **Select Highlighted Point**.

С	Multiple Points F	ound					- 🗆	\times
Ca	ncel					Se	elect Highlighted I	Point
	Point No	East (m)	North (m)	Elevation (m)	Feature Code	Comment	Is Deviation already	
)	18184	740598.400	6303115.240	664.060	1 - Point of intersection(PI)			
	17834	740596.840	6303115.650	664.050	2 - Ground			
	17871	740597.050	6303113.960	663.950	2 - Ground			
	17905	740597.240	6303114.440	664.010	2 - Ground			
	17917	740597.280	6303116.010	664.160	2 - Ground			
	17922	740597.300	6303115.120	664.070	2 - Ground			
	17966	740597.530	6303113.550	663.990	2 - Ground			
	18038	740597.890	6303116.150	664.260	2 - Ground			
	18075	740598.020	6303114.910	664.110	2 - Ground			
	18089	740598.070	6303113.600	664.030	2 - Ground			
	18195	740598.450	6303114.450	664.150	2 - Ground			
	18199	740598.470	6303115.150	664.170	2 - Ground			
	18214	740598.530	6303116.080	664.280	2 - Ground			
	18268	740598.740	6303113.550	664.050	2 - Ground			

13. Do the same for the other 2 points with the red cross. The point numbers are 33187 and 46314. The screen should now look like this.





The blue/purple envelopes show which aerial points will be visible in the profile view. It is best to match this to the type of data. Currently in this job the vale is set to 10m either side of the centreline. Reduce this value to 2m.

14. Change the envelope width by entering a new value as shown in the image below. Note that the envelopes decrease in size.



15. Select the menu option **Create Profile** as shown below.



The form below will be displayed. Here you can change the Design and Profile name. The creation of the centreline is also a multithreaded process and the speed of the process depends on the point cloud density, number of triangles and number of spans.

16. Select Create Profile

Create Design and Profile for Digital Terrain Model		x
Design Name Design1		Create Profile
Profile Name Profile 1		Cancel
Setup for Centreline Creation	Thread1	_
Threads Completed		
Join Data from Threads		
Aerial Points Extracted		

The number of threads used depends on how many spans are being processed. In this case there are only 2 spans, so only 2 threads are used as shown below. You will be notified with a message box when the process has completed.

Create Design and Pr	rofile for Digital Terrain Model		×
Design Name Profile Name	Design1 Profile1		Create Profile Cancel
☑ Setup for i ☑ Threads C ☑ Join Data I		Thread1 Thread2	
🗹 Aerial Poir	ts Extracted		



The view will now change to show a line between the pole locations as shown below.



17. Switch to the Profile view by selecting **Profiles** as shown below.

COLDNet Profile Version: 1.0.1 Licenced to:													
File Design Parameters & Libraries Terrain Data Profiles	Conductors Tables											Cross-Secti	
Create DTM from Lidar Deviation Point Deviation at all poles Clear Point Selection Envelope Width (m) : 2						Feature Codes Generate Profile							



You should see this view below.